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(54) **INDUSTRIAL ROBOT**

(71) Applicant: **NIDEC SANKYO CORPORATION**,
Nagano (JP)

(72) Inventors: **Takayuki Yazawa**, Nagano (JP);
Yutaka Yoshizawa, Nagano (JP);
Masashi Fujiwara, Nagano (JP)

(73) Assignee: **NIDEC SANKYO CORPORATION**,
Nagano (JP)

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Primary Examiner — William Kelleher

Assistant Examiner — Randell J Krug

(74) *Attorney, Agent, or Firm* — Cantor Colburn LLP

(57) **ABSTRACT**

An industrial robot may include a main body part; a plurality of levers having base end sides turnably connected with the main body part; a plurality of arm parts having respective base end sides turnably connected with respective tip end sides of the plurality of the levers; a movable part which is turnably connected with the respective tip end sides of the plurality of the arm parts; and a plurality of turning drive mechanisms for respectively turning the plurality of the levers. The plurality of the levers may radially extend to an outer peripheral side of the main body part at a substantially equal pitch. The arm part may provided with two arms which are mutually parallel to each other and are formed in a straight shape.

5 Claims, 10 Drawing Sheets

